

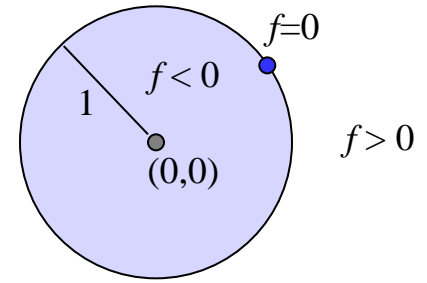
Volume and Solid Modeling

CS418 Computer Graphics

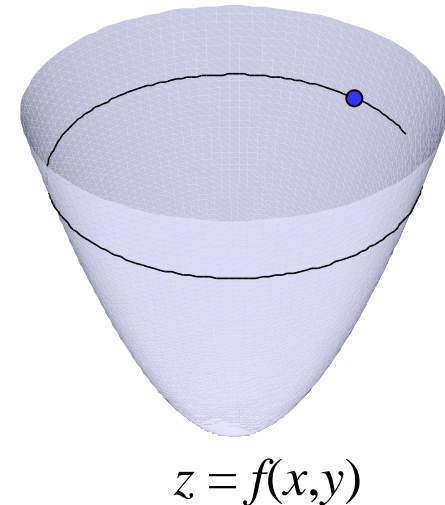
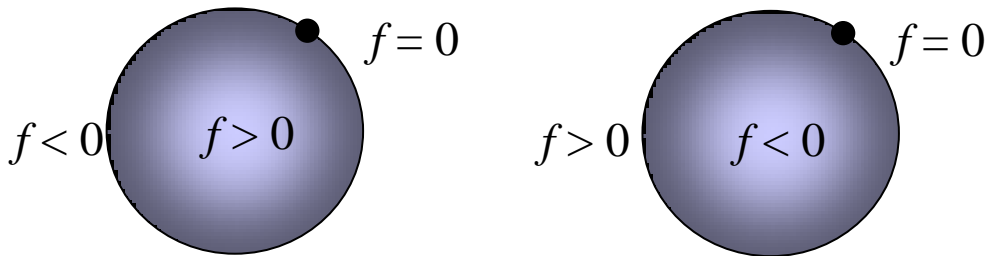
John C. Hart

Implicit Surfaces

- Real function $f(x,y,z)$
- Classifies points in space
- Image synthesis (sometimes)
 - inside $f > 0$
 - outside $f < 0$
 - on the surface $f = 0$
- CAGD: inside $f < 0$, outside $f > 0$
- Surface $f^{-1}(0)$: Manifold if zero is a regular value of f

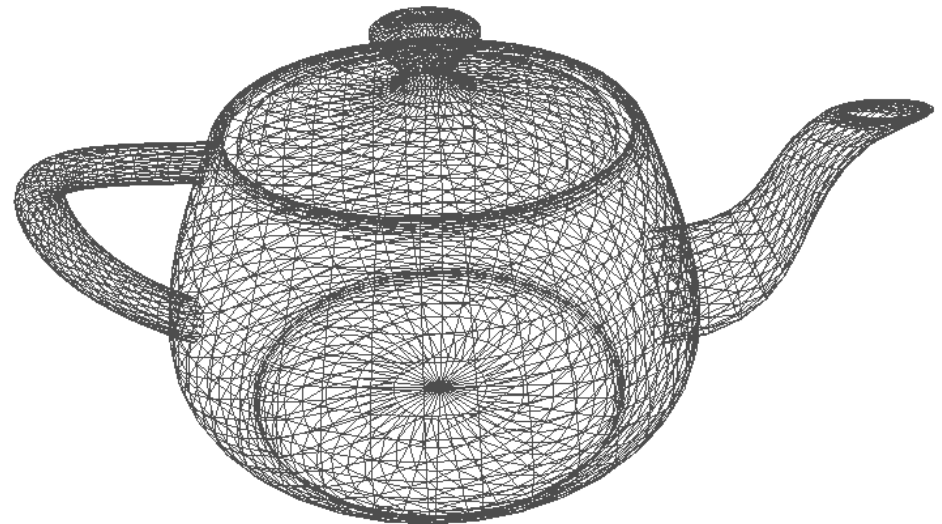
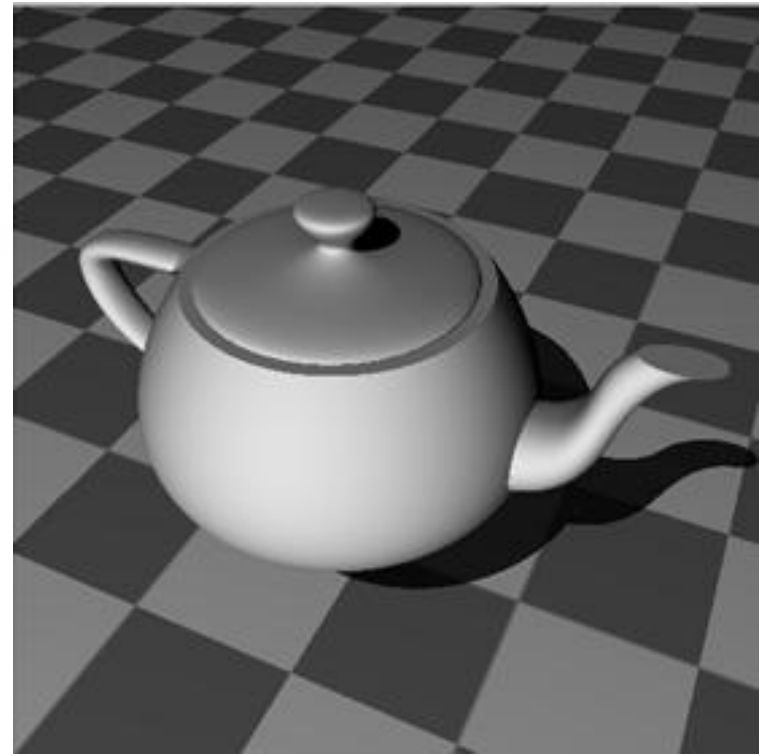


Circle example
 $f(x,y) = x^2 + y^2 - 1$



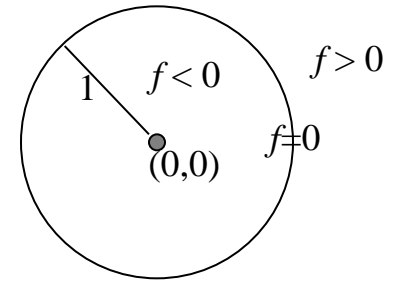
Why Use Implicits?

- v. polygons
 - smoother
 - compact, fewer higher-level primitives
 - harder to display in real time
- v. parametric patches
 - easier to blend
 - no topology problems
 - lower degree
 - harder to parameterize
 - easier to ray trace
 - well defined interior

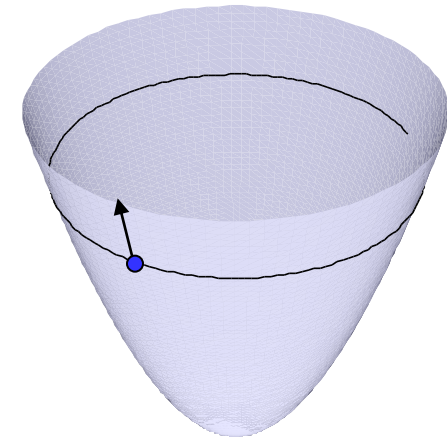


Surface Normals

- Surface normal usually gradient of function
$$\nabla f(x,y,z) = (\delta f/\delta x, \delta f/\delta y, \delta f/\delta z)$$
- Gradient not necessarily unit length
- Gradient points in direction of increasing f
 - Outward when $f < 0$ denotes interior
 - Inward when $f > 0$ denotes interior



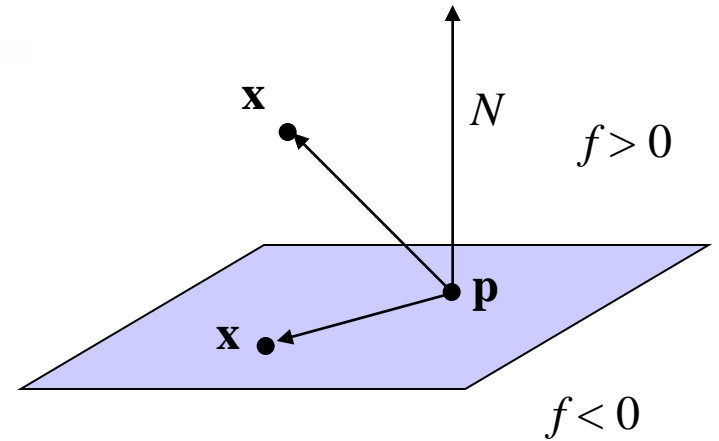
Circle example
 $f(\mathbf{x}) = x^2 + y^2 - 1$
 $\mathbf{x} = (x,y)$



$$z = f(x,y)$$

Plane

- Plane bounds half-space
- Specify plane with point \mathbf{p} and normal N
- Points in plane \mathbf{x} are perp. to normal N
- f is distance if $\|N\| = 1$

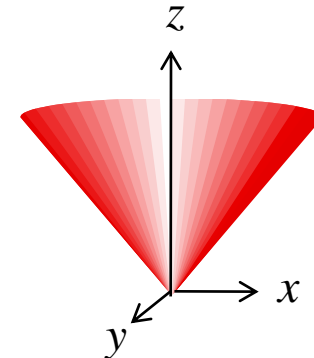
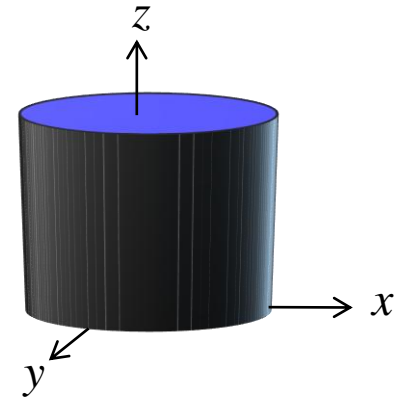


$$f(\mathbf{x}) = (\mathbf{x} - \mathbf{p}) \cdot N$$

Quadrics

$$f(x,y,z) = Ax^2 + 2Bxy + 2Cxz + 2Dx + Ey^2 + 2Fyz + 2Gy + Hz^2 + 2Iz + J$$

- Sphere: $f(x,y,z) = x^2 + y^2 + z^2 - 1$
- Cylinder: $f(x,y,z) = x^2 + y^2 - 1$
- Cone: $f(x,y,z) = x^2 + y^2 - z^2$
- Paraboloid: $Ax^2 + Ey^2 - 2Iz = 0$



Homogeneous Quadrics

$$f(\mathbf{x}) = \mathbf{x}^T Q \mathbf{x}$$

$$f(x, y, z) = \begin{bmatrix} x & y & z & 1 \end{bmatrix}$$

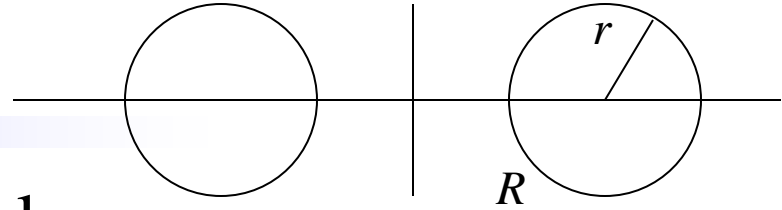
$$\begin{bmatrix} A & B & C & D \\ B & E & F & G \\ C & F & H & I \\ D & G & I & J \end{bmatrix} \begin{bmatrix} x \\ y \\ z \\ 1 \end{bmatrix}$$

Homogeneous coordinates

- $[x \ y \ z \ w]$
- Divide by w to find actual coords: $[x/w \ y/w \ z/w \ 1]$

Transforming quadrics
 $\mathbf{x} Q \mathbf{x}^T = 0, \quad \mathbf{x}' = \mathbf{x}T$
 find Q' s.t. $\mathbf{x}' Q' \mathbf{x}'^T = 0$
 $\mathbf{x} = \mathbf{x}' T^*$ since \mathbf{x} homo.
 $\mathbf{x}' T^* Q (\mathbf{x}' T^*)^T = 0$
 $\mathbf{x}' (T^* Q T^{*T}) \mathbf{x}'^T = 0$
 $Q' = T^* Q T^{*T}$

Torus



- Product of two implicit circles

$$(x - R)^2 + z^2 - r^2 = 0$$

$$(x + R)^2 + z^2 - r^2 = 0$$

$$((x - R)^2 + z^2 - r^2)((x + R)^2 + z^2 - r^2)$$

$$(x^2 - Rx + R^2 + z^2 - r^2)(x^2 + Rx + R^2 + z^2 - r^2)$$

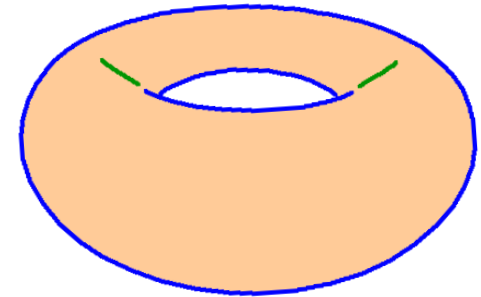
$$x^4 + 2x^2z^2 + z^4 - 2x^2r^2 - 2z^2r^2 + r^4 + 2x^2R^2 + 2z^2R^2 - 2r^2R^2 + R^4$$

$$(x^2 + z^2 - r^2 - R^2)^2 + 4z^2R^2 - 4r^2R^2$$

- Surface of rotation

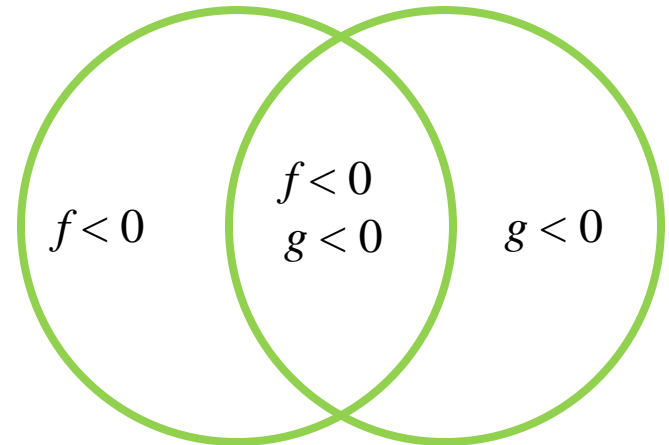
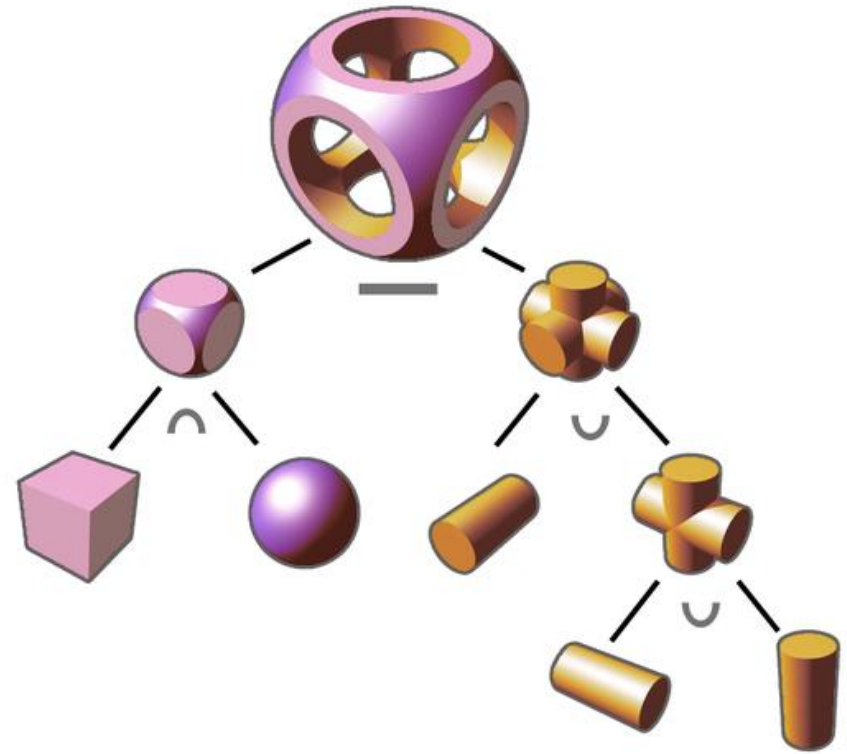
replace x^2 with $x^2 + y^2$

$$f(x,y,z) = (x^2 + y^2 + z^2 - r^2 - R^2)^2 + 4R^2(z^2 - r^2)$$



CSG

- Assume $f < 0$ inside
- CSG ops by min/max ops
 - Union: $\min f, g$
 - Intersection: $\max f, g$
 - Complement: $-f$
 - Subtraction: $\max f, -g$
- Problem: C^1 discontinuity
- Can we smooth the blend crease?



Blobs

- Blinn TOG 1(3) 1982
- Sum of Gaussians

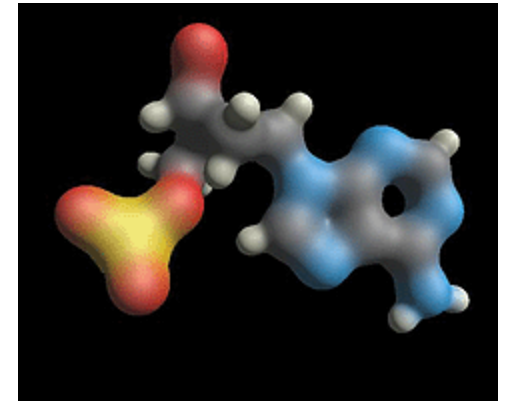
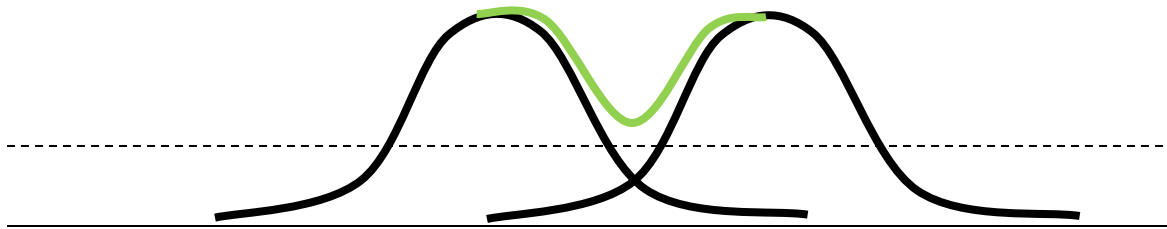
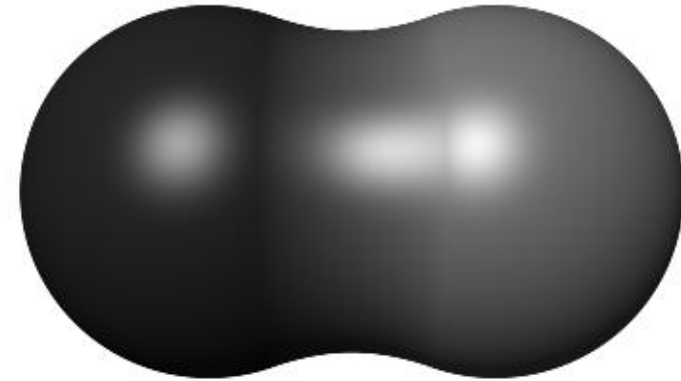
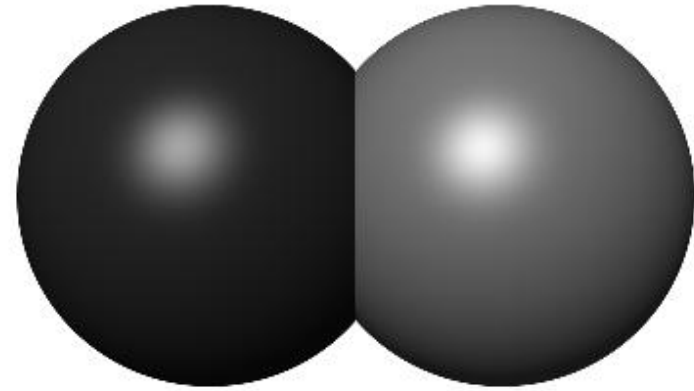
$$r_i^2(x,y,z) = x^2 + y^2 + z^2$$

$$f(\mathbf{x}) = -1 + \sum \exp(-(B_i/R_i^2)r_i^2 + B_i)$$

B – blobbiness (positive)

R – radius of blob at rest

r – radius function



Soft Objects

- Wyvill, McPheeters & Wyvill VC 86
- Exponential: too expensive, non-local
- Approximate $\exp(-r^2)$ with polynomial $C()$

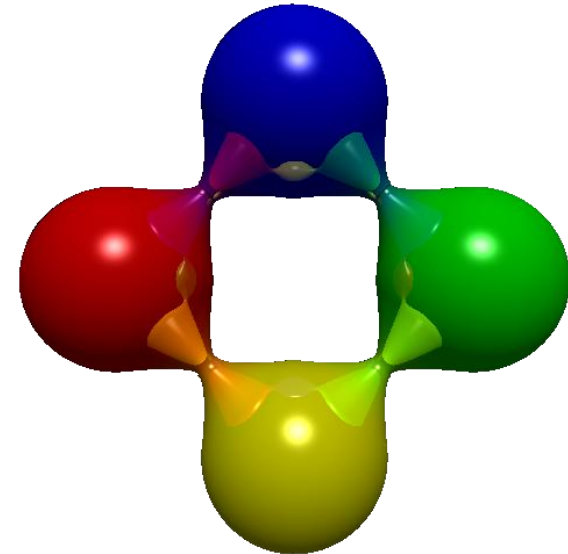
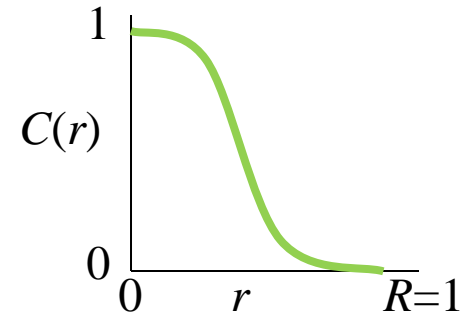
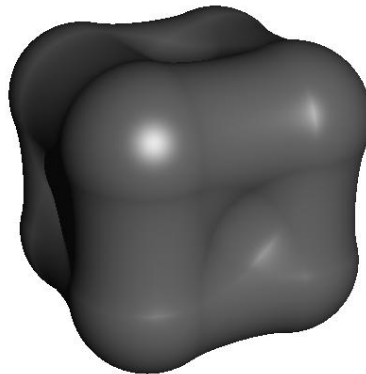
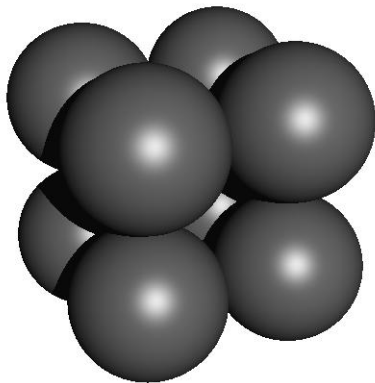
$$C(0) = 1, C(R) = 0, C'(0) = 0, C'(R) = 0$$

$$C(r^2) = -(4/9)r^6/R^6 + (17/9)r^4/R^4 - (22/9)r^2/R^2 + 1$$

$$C(r) = 2r^3/R^3 - 3r^2/R^2 + 1$$

$$C(r) = (1 - r^2/R^2)^3 \quad (G^2 \text{ continuity})$$

Pair of quadratics (metaballs)



Marching Cubes

Read volume in two slices at a time

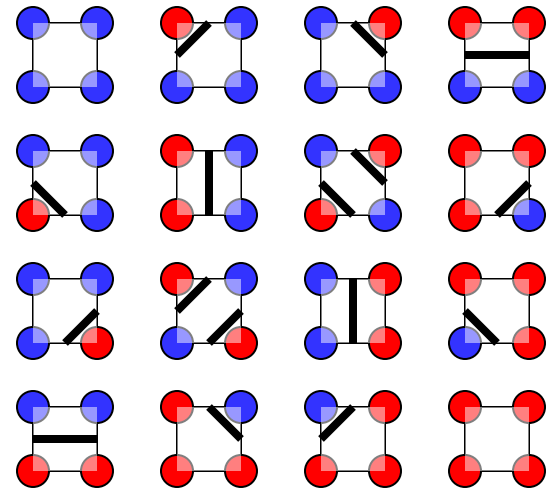
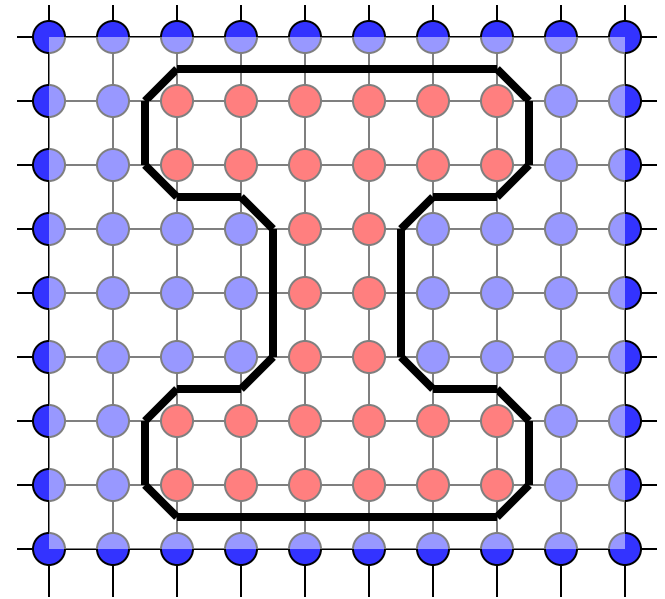
For each cubic cell

Compute index using bitmask of vertices

Output polygon(s) stored at index translated to cell position

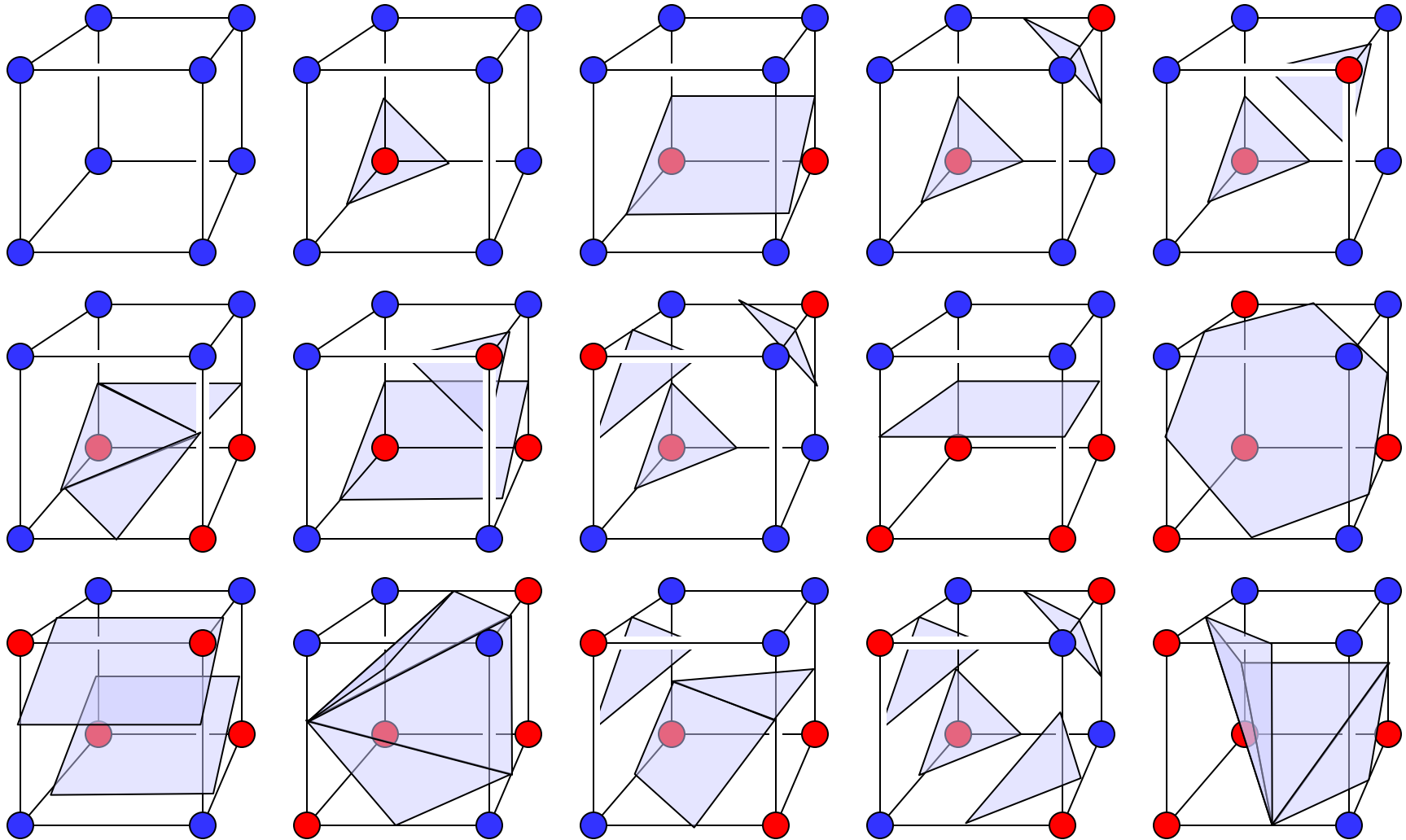
End for

Remove last slice, add new slice, repeat



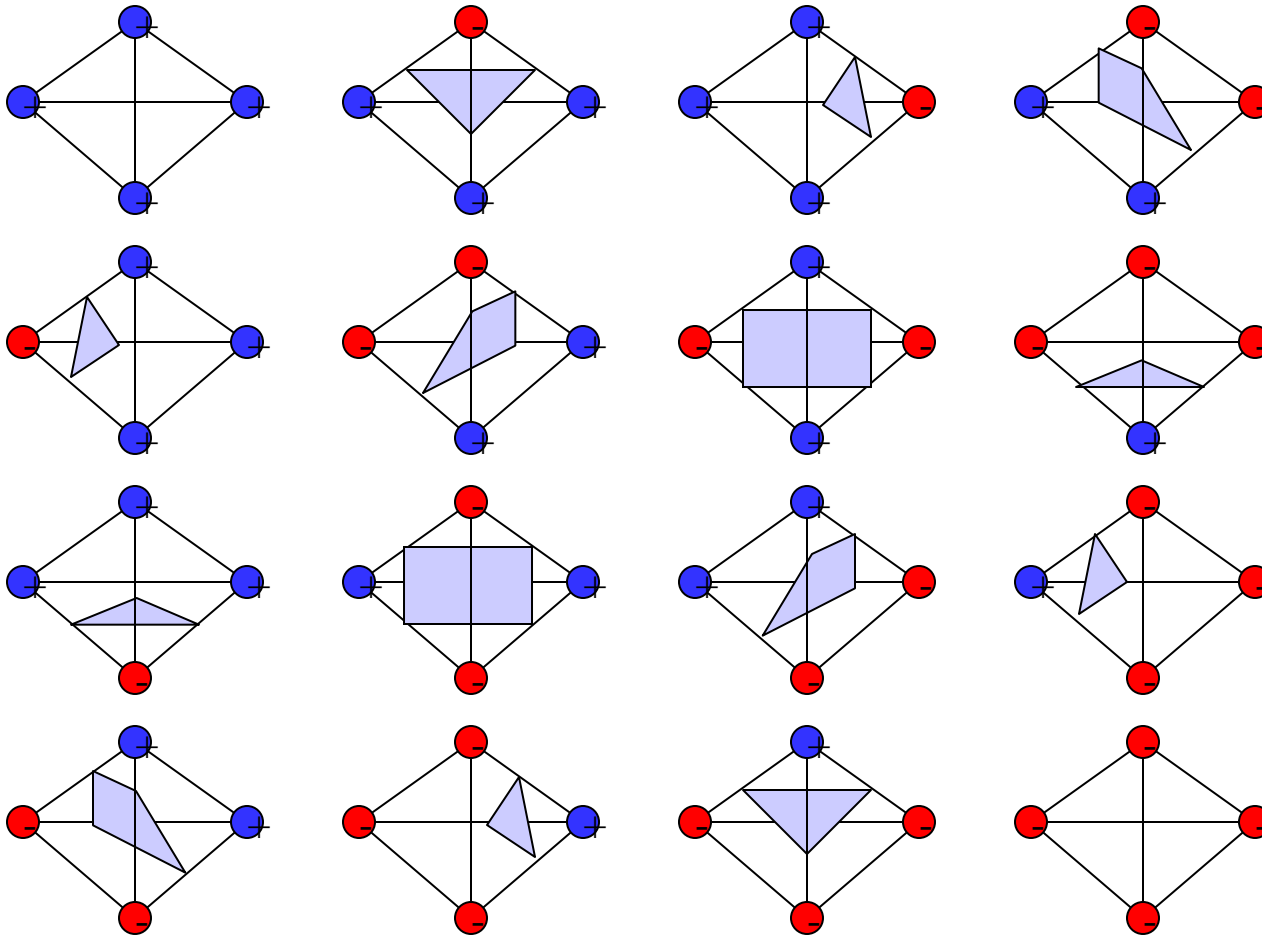
Marching Cube Cases

256 in all
15 modulo symmetry



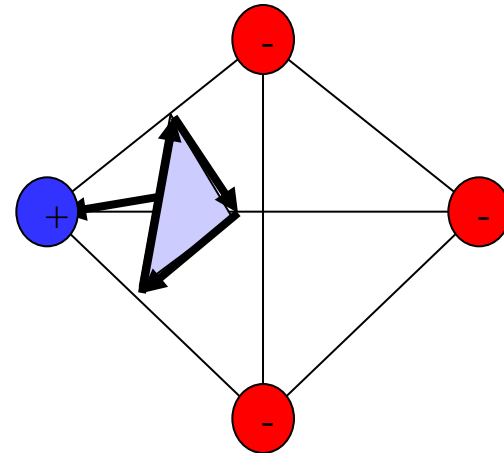
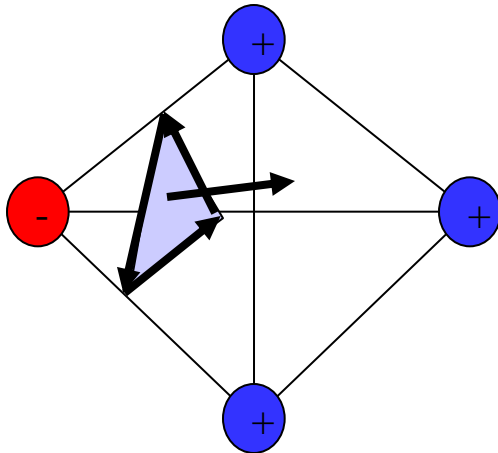
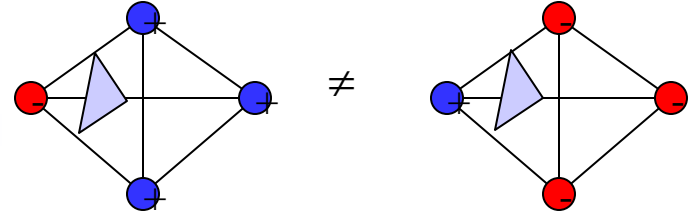
Marching Tet Cases

16 in all
3 modulo symmetry



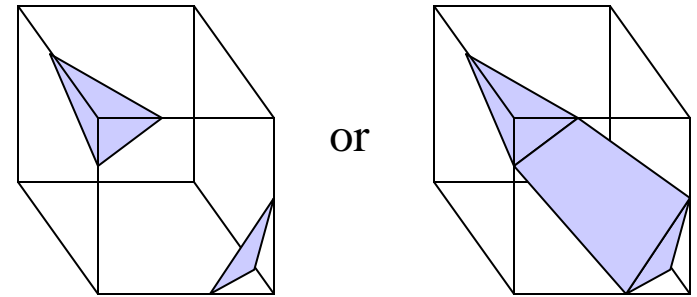
Orientation

- Consistency allows polygons to be drawn with correct orientation
- Supports backface culling

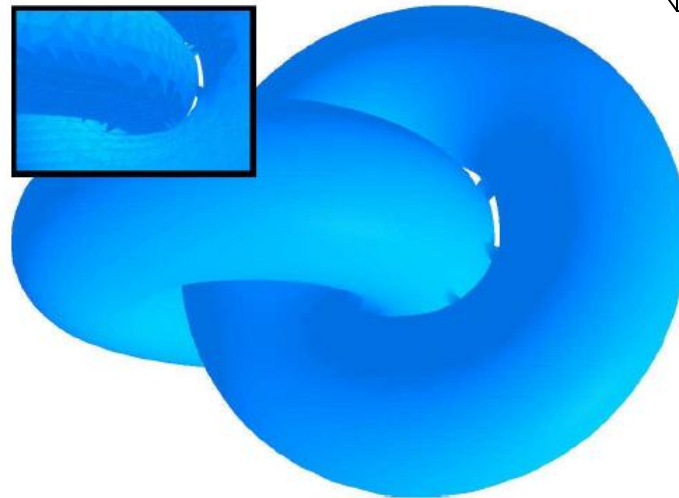
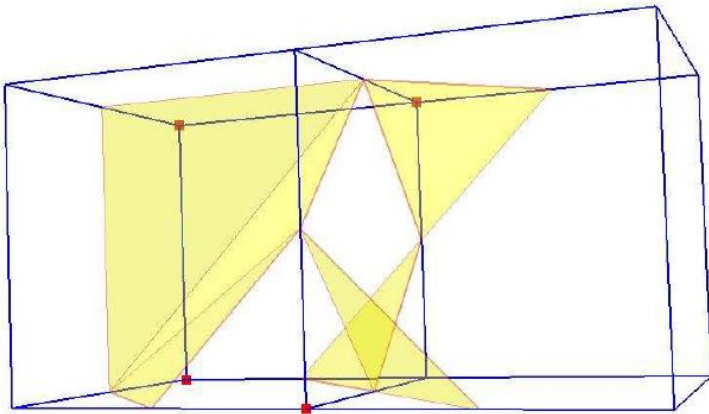
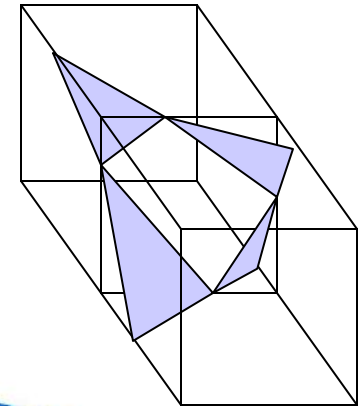


Problem: Ambiguity

- Some cell corner value configurations yield more than one consistent polygon
- Only for cubes, not tetrahedra (why?)
- In 3-D can yield holes in surface!
- How can we resolve these ambiguities?

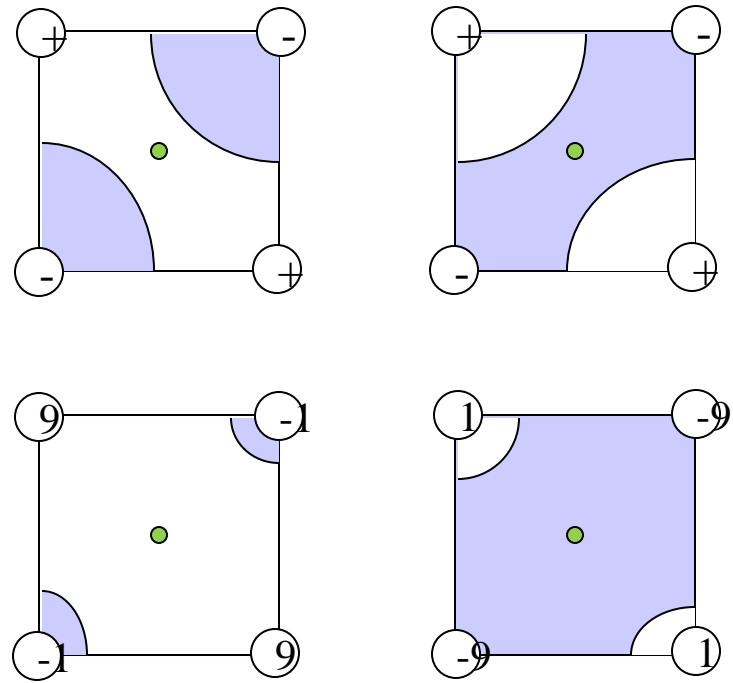


or



Problem: Ambiguity

- Some cell corner value configurations yield more than one consistent polygon
- Only for cubes, not tetrahedra (why?)
- In 3-D can yield holes in surface!
- How can we resolve these ambiguities?
- Topological Inference
 - Sample a point in the center of the ambiguous face
 - If data is discretely sampled, bilinearly interpolate samples



$$p(s,t) = (1-s)(1-t) a + s(1-t) b + (1-s) t c + s t d$$

Problem: Ambiguity

- Some cell corner value configurations yield more than one consistent polygon
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- In 3-D can yield holes in surface!
- How can we resolve these ambiguities?
- Topological Inference
 - Sample a point in the center of the ambiguous face
 - If data is discretely sampled, bilinearly interpolate samples
- Preferred Polarity
 - Encode preference into table
 - \equiv cubes \rightarrow tets
 - MC edges across neighboring faces must share direction to avoid cracks/holes

